



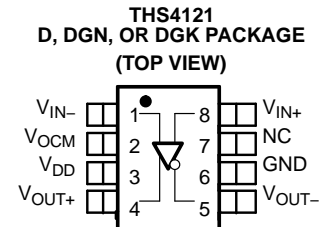
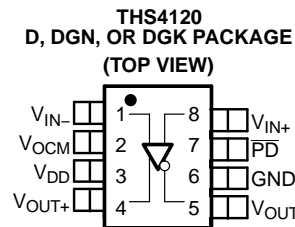
## HIGH-SPEED FULLY DIFFERENTIAL I/O AMPLIFIERS

### FEATURES

- **High Performance**
  - 100 MHz, –3 dB Bandwidth
  - 50 V/μs Slew Rate
  - 75 dB Total Harmonic Distortion at 1 MHz ( $V_O = 2 V_{PP}$ )
  - 5.4 nV/√Hz Input-Referred Noise (10 kHz)
- **Differential Input/Differential Output**
  - Balanced Outputs Reject Common-Mode Noise
  - Differential Reduced Second Harmonic Distortion
- **Power Supply Range**
  - $V_{DD} = 3.3 V$

### KEY APPLICATIONS

- Simple Single-Ended To Differential Conversion
- Differential ADC Driver/Differential Antialiasing
- Differential Transmitter and Receiver
- Output Level Shifter



### DESCRIPTION

The THS412x is one in a family of fully differential-input, differential-output devices fabricated using Texas Instruments' state-of-the-art submicron CMOS process.

The THS412x consists of a true fully-differential signal path from input to output. This results in excellent common-mode noise rejection and improved total harmonic distortion.

### HIGH-SPEED DIFFERENTIAL I/O FAMILY

DEVICE	NUMBER OF CHANNELS	POWERDOWN
THS4120 <sup>(1)</sup>	1	Yes
THS4121	1	–

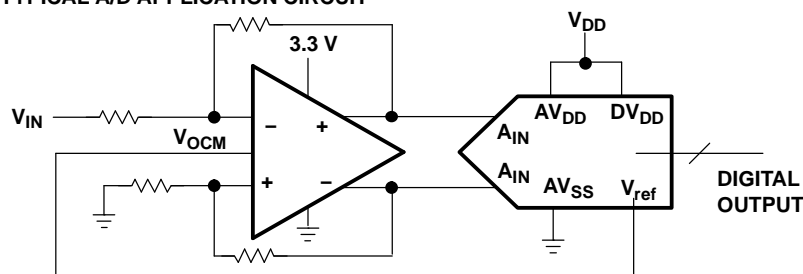
(1) For proper functionality, an external 10-kΩ pullup resistor is required between the PD pin and the positive supply.

### RELATED DEVICES

DEVICE <sup>(1)</sup>	DESCRIPTION	SINGLE SUPPLY VOLTAGE RANGE	SPLIT SUPPLY VOLTAGE RANGE
THS413x	150 MHz, 51 V/μs, 1.3 nV/√Hz	5 V to 30 V	±2.5 to ±15
THS414x	160 MHz, 450 V/μs, 6.5 nV/√Hz	5 V to 30 V	±2.5 to ±15
THS415x	150 MHz, 650 V/μs, 7.6 nV/√Hz	5 V to 30 V	±2.5 to ±15

(1) See the TI Web site for additional high-speed amplifier devices.

### TYPICAL A/D APPLICATION CIRCUIT



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

PowerPAD is a trademark of Texas Instruments.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### AVAILABLE OPTIONS

T <sub>A</sub>	PACKAGED DEVICES					EVALUATION MODULES
	SMALL OUTLINE(D)	MSOP PowerPAD™		MSOP		
		(DGN)	SYMBOL	(DGK)	SYMBOL	
0°C to 70°C	THS4120CD	THS4120CDGN	ARL	THS4120CDGK	ATZ	THS4120EVM
	THS4121CD	THS4121CDGN	ASB	THS4121CDGK	ATO	THS4121EVM
-40°C to 85°C	THS4120ID	THS4120IDGN	ARM	THS4120IDGK	ARN	—
	THS4121ID	THS4121IDGN	ASC	THS4121IDGK	ASN	—

### ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted) <sup>(1)</sup>

		UNIT	
Supply voltage, GND to V <sub>DD</sub>		3.6 V	
V <sub>I</sub>	Input voltage	±V <sub>DD</sub>	
I <sub>O</sub>	Output current (sink) <sup>(2)</sup>	110 mA	
V <sub>ID</sub>	Differential input voltage	±V <sub>DD</sub>	
Continuous total power dissipation		See Dissipation Rating Table	
T <sub>J</sub>	Maximum junction temperature <sup>(3)</sup>	150°C	
T <sub>J</sub>	Maximum junction temperature, continuous operation, long-term reliability <sup>(4)</sup>	125°C	
T <sub>A</sub>	Operating free-air temperature	C suffix	0°C to 70°C
		I suffix	-40°C to 85°C
T <sub>stg</sub>	Storage Temperature	-65°C to 150°C	
Lead temperature 1,6 mm (1/16 Inch) from case for 10 seconds		300°C	
ESD ratings	HBM	4000 V	
	CDM	1500 V	
	MM	200 V	

- (1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) The THS412x may incorporate a PowerPad™ on the underside of the chip. This acts as a heatsink and must be connected to a thermally dissipative plane for proper power dissipation. Failure to do so may result in exceeding the maximum junction temperature which could permanently damage the device. See TI technical brief [SLMA002](#) and [SLMA004](#) for more information about utilizing the PowerPad™ thermally enhanced package.
- (3) The absolute maximum temperature under any condition is limited by the constraints of the silicon process.
- (4) The maximum junction temperature for continuous operation is limited by package constraints. Operation above this temperature may result in reduced reliability and/or lifetime of the device.

### DISSIPATION RATING TABLE

PACKAGE	θ <sub>JA</sub> <sup>(1)</sup> (°C/W)	θ <sub>JC</sub> (°C/W)	POWER RATING <sup>(2)</sup>	
			T <sub>A</sub> = 25°C	T <sub>A</sub> = 85°C
D	97.5	38.3	1.02 W	410 mW
DGN	58.4	4.7	1.71 W	685 mW
DGK	260	54.2	385 mW	154 mW

- (1) This data was taken using the JEDEC standard High-K test PCB.
- (2) Power rating is determined with a junction temperature of 125°C. This is the point where distortion starts to substantially increase. Thermal management of the final PCB should strive to keep the junction temperature at or below 125°C for best performance and long-term reliability.

## RECOMMENDED OPERATING CONDITIONS

		MIN	TYP	MAX	UNIT	
V <sub>DD</sub>	Supply voltage	Split supply	±1.5	±1.65	±1.75	V
		Single supply	3	3.3	3.5	
T <sub>A</sub>	Operating free-air temperature	C suffix	0		70	°C
		I suffix	−40		85	

## ELECTRICAL CHARACTERISTICS

V<sub>DD</sub> = 3.3 V, R<sub>L</sub> = 800 Ω, T<sub>A</sub> = 25°C (unless otherwise noted)<sup>(1)</sup>

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT	
<b>DYNAMIC PERFORMANCE</b>								
BW	Small-signal bandwidth (−3 dB)	V <sub>DD</sub> = 3.3 V,	Gain = 1, R <sub>f</sub> = 200 Ω		100		MHz	
SR	Slew rate <sup>(2)</sup>	V <sub>DD</sub> = 3.3 V,	Gain = 1		55		V/μs	
t <sub>s</sub>	Settling time to 0.1%	Differential step voltage = 2 V <sub>PP</sub> ,	Gain = 1		60		ns	
	Settling time to 0.01%				292			
<b>DISTORTION PERFORMANCE</b>								
THD	Total harmonic distortion Differential input, differential output Gain = 1, R <sub>f</sub> = 200 Ω, R <sub>L</sub> = 800 Ω, V <sub>O</sub> = 2 V <sub>PP</sub>	V <sub>DD</sub> = 3.3 V,	f = 1 MHz		−75		dB	
THD	Total harmonic distortion Differential input, differential output Gain = 1, R <sub>f</sub> = 200 Ω, R <sub>L</sub> = 800 Ω, V <sub>O</sub> = 4 V <sub>PP</sub>	V <sub>DD</sub> = 3.3 V,	f = 1 MHz		−66		dB	
	Spurious free dynamic range (SFDR) Differential input, differential output, V <sub>O</sub> = 4 V <sub>PP</sub>	R <sub>f</sub> = 200 Ω,	f = 1 MHz		−69		dB	
	Third intermodulation distortion	V <sub>I</sub> = 0.071 V <sub>RMS</sub>	Gain = 1, f = 10 MHz		−75		dBc	
<b>NOISE PERFORMANCE</b>								
V <sub>n</sub>	Input voltage noise	f = 10 kHz			5.4		nV/√Hz	
I <sub>n</sub>	Input current noise	f = 10 kHz			1		fA/√Hz	
<b>DC PERFORMANCE</b>								
Open-loop gain		T <sub>A</sub> = 25°C		60	66		dB	
		T <sub>A</sub> = full range			66			
V <sub>S</sub>	Input offset voltage	T <sub>A</sub> = 25°C			3	8	mV	
		T <sub>A</sub> = full range			4	9		
	Input offset voltage, referred to V <sub>OCM</sub>	T <sub>A</sub> = 25°C				5		13
		T <sub>A</sub> = full range						14
Offset voltage drift		T <sub>A</sub> = full range			25		μV/°C	
I <sub>IB</sub>	Input bias current	T <sub>A</sub> = full range			1.2		pA	
I <sub>OS</sub>	Input offset current	T <sub>A</sub> = full range			100		fA	
Current offset drift		T <sub>A</sub> = full range			5		fA/°C	

(1) The full range temperature is 0°C to 70°C for the C suffix, and −40°C to 85°C for the I suffix.

(2) Slew rate is measured differentially from an output level range of 25% to 75%.

## ELECTRICAL CHARACTERISTICS (Continued)

$V_{DD} = 3.3\text{ V}$ ,  $R_L = 800\ \Omega$ ,  $T_A = 25^\circ\text{C}$  (unless otherwise noted)<sup>(1)</sup>

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>INPUT CHARACTERISTICS</b>						
CMRR	Common-mode rejection ratio	$T_A = \text{full range}$	64	96		dB
$V_{ICR}$	Common-mode input voltage range	$T_A = \text{full range}$	0.65 to $V_{DD} - 0.1$	0.35 to $V_{DD}$		V
$r_i$	Input resistance (dc level)	Measured into each input terminal		820		M $\Omega$
$C_i$	Input capacitance, closed loop			3		pF
$r_o$	Output resistance	See Figure 16		1		$\Omega$
<b>OUTPUT CHARACTERISTICS</b>						
$V_{OH}$	High-level output Voltage	$V_{IC} = V_{DD}/2$ , $V_{DD} = 3.3\text{ V}$ , $T_A = 25^\circ\text{C}$	3.05	3.15		V
$V_{OL}$	Low-level output Voltage	$V_{IC} = V_{DD}/2$ , $V_{DD} = 3.3\text{ V}$ , $T_A = 25^\circ\text{C}$	0.25	0.15		V
$I_O$	Output current (sink), $R_L = 7\ \Omega$	$V_{DD} = 3.3\text{ V}$ , $T_A = 25^\circ\text{C}$	80	100		mA
$I_O$	Output current (source), $R_L = 7\ \Omega$	$V_{DD} = 3.3\text{ V}$ , $T_A = 25^\circ\text{C}$	20	25		mA
<b>POWER SUPPLY</b>						
$V_{DD}$	Supply voltage range	Single supply		3.3		V
$I_{DD}$	Quiescent current (per amplifier)	$V_{DD} = 3.3\text{ V}$	$T_A = 25^\circ\text{C}$	11	13.5	mA
			$T_A = \text{full range}$		16	
PSRR	Power supply rejection ratio	$T_A = 25^\circ\text{C}$	68	85		dB
<b>POWER-DOWN CHARACTERISTICS (THS4120 ONLY)</b>						
	Power-down voltage level <sup>(2)</sup>	Enable		>1.4		V
		Power-down		<1.2		
	Power-down quiescent current	$T_A = 25^\circ\text{C}$		120		$\mu\text{A}$
		$T_A = \text{full range}$		130		
$t_{on}$	Turn-on time delay	50% of final supply current value		4.8		$\mu\text{s}$
$t_{off}$	Turn-off time delay			3		ns
$z_o$	Output impedance	$f = 1\text{ MHz}$		1		k $\Omega$

(1) The full range temperature is  $0^\circ\text{C}$  to  $70^\circ\text{C}$  for the C suffix, and  $-40^\circ\text{C}$  to  $85^\circ\text{C}$  for the I suffix.

(2) For detail information on the power-down circuit, see the power-down section in the application section of this data sheet.

## TYPICAL CHARACTERISTICS

### Table of Graphs

			FIGURE
	Small-signal frequency response		1
SR	Slew rate		2
THD	Total harmonic distortion	vs Frequency	3
		vs Output voltage	4
	Harmonic distortion	vs Frequency	5, 6, 7
		vs Output voltage	8, 9
	Third intermodulation distortion	vs Output voltage	10
$V_O$	Output voltage	vs Load resistance	11
	Settling time		12
$V_n$	Voltage noise	vs Frequency	13
$V_{OO}$	Output offset voltage	vs Common-mode input voltage	14
CMMR	Common-mode rejection ratio	vs Frequency	15
$z_{os}$	Single-ended output impedance (closed loop)	vs Frequency	16
$z_o$	Single-ended ( $V_{OCM}$ ) input impedance	vs Frequency	17

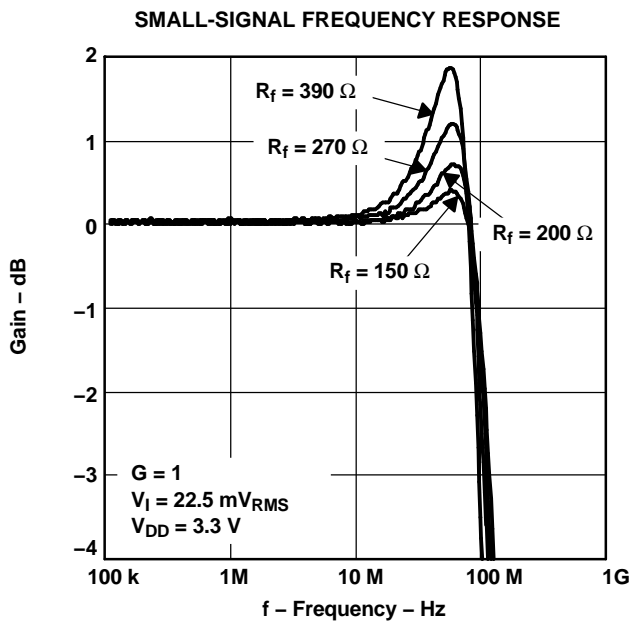


Figure 1.

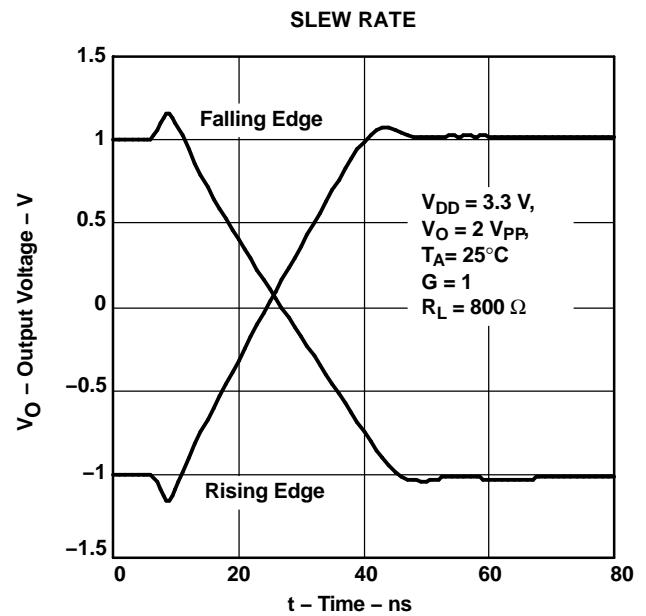


Figure 2.

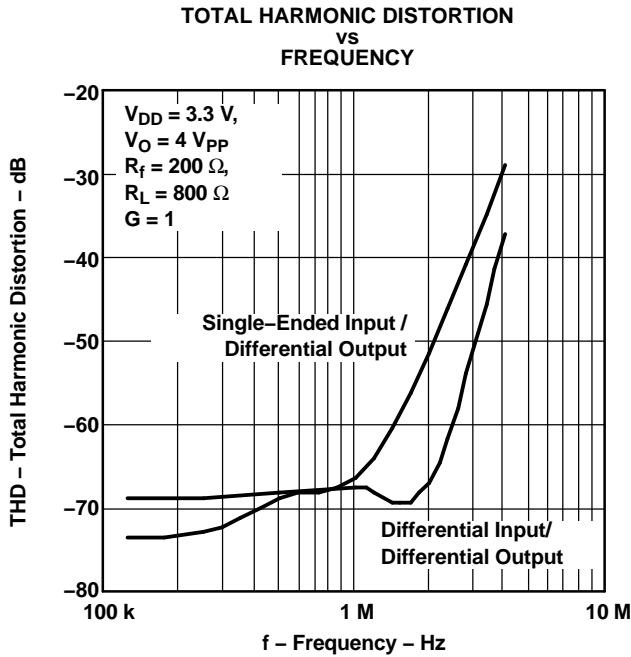


Figure 3.

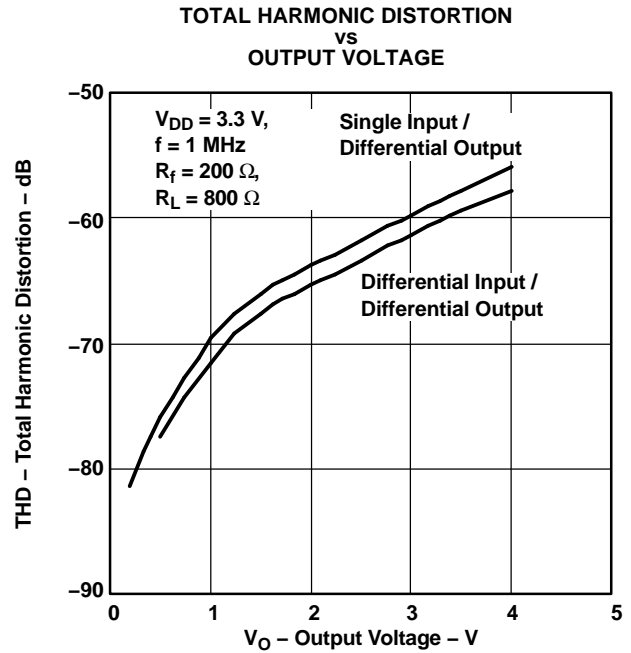


Figure 4.

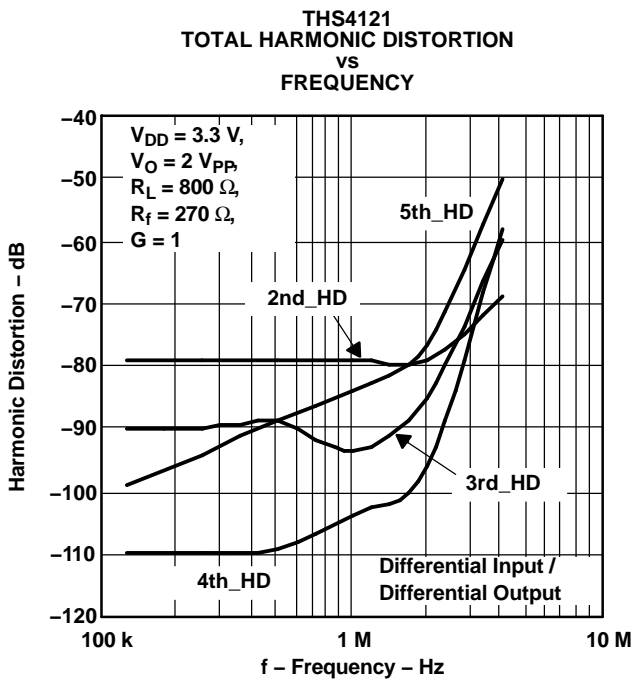


Figure 5.

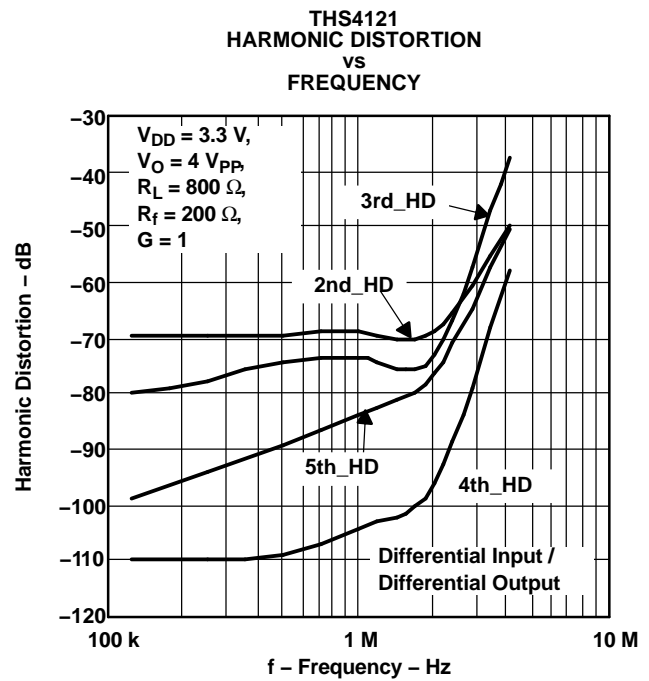


Figure 6.

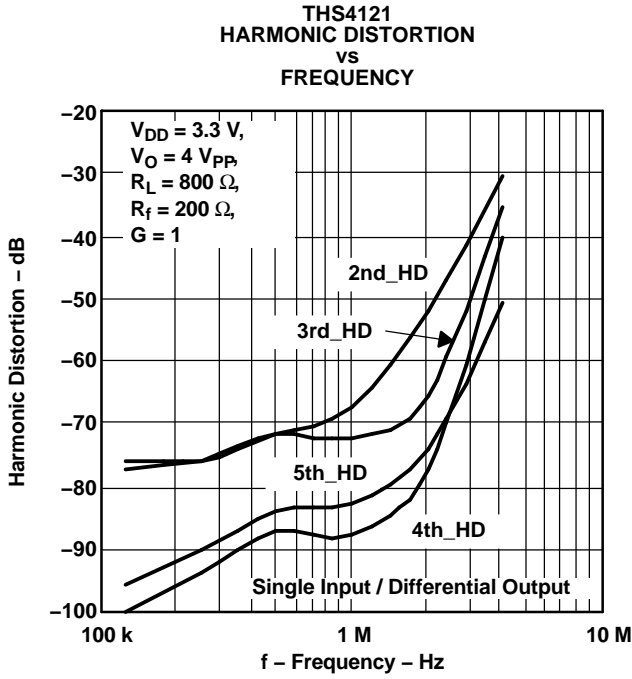


Figure 7.

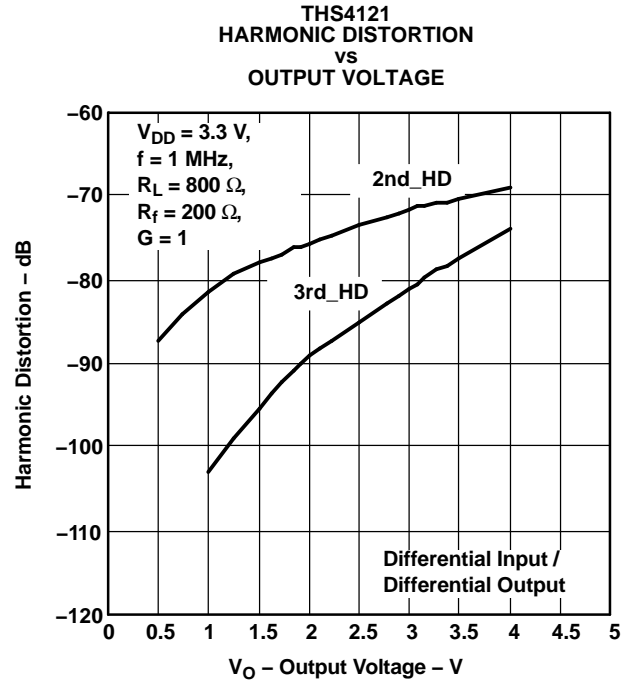


Figure 8.

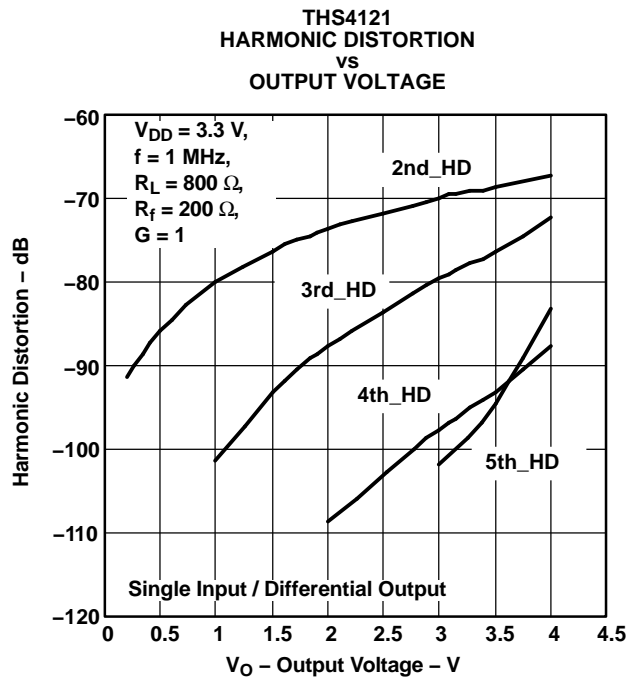


Figure 9.

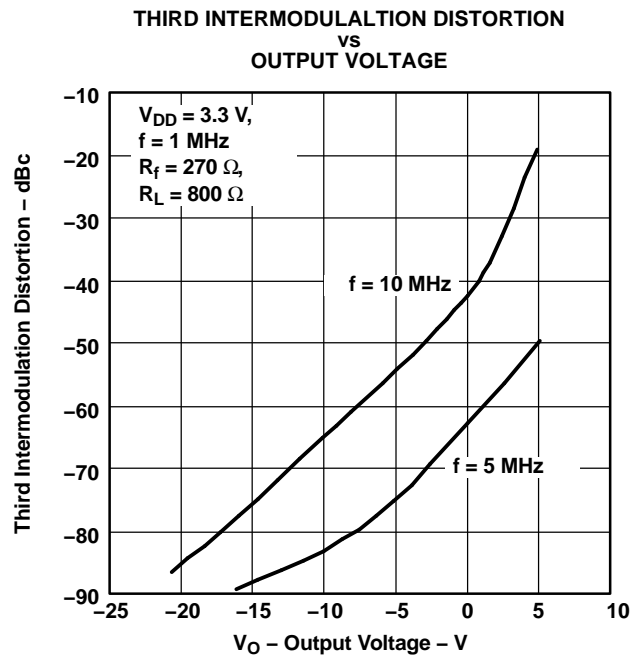


Figure 10.

THS4121  
OUTPUT VOLTAGE  
vs  
LOAD RESISTANCE

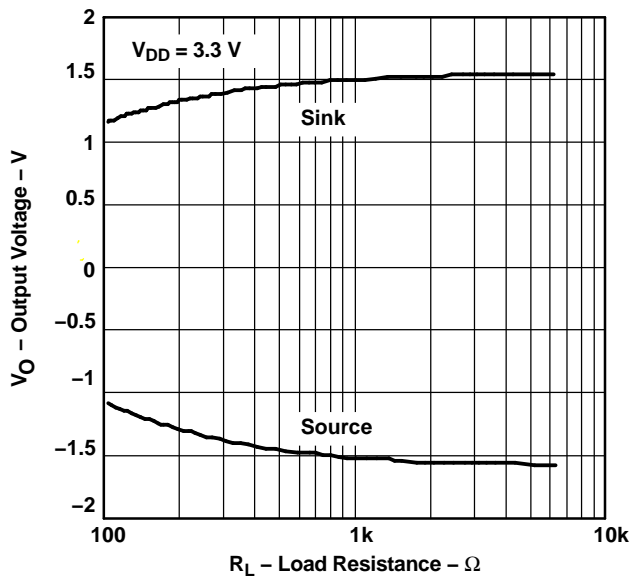


Figure 11.

SETTLING TIME

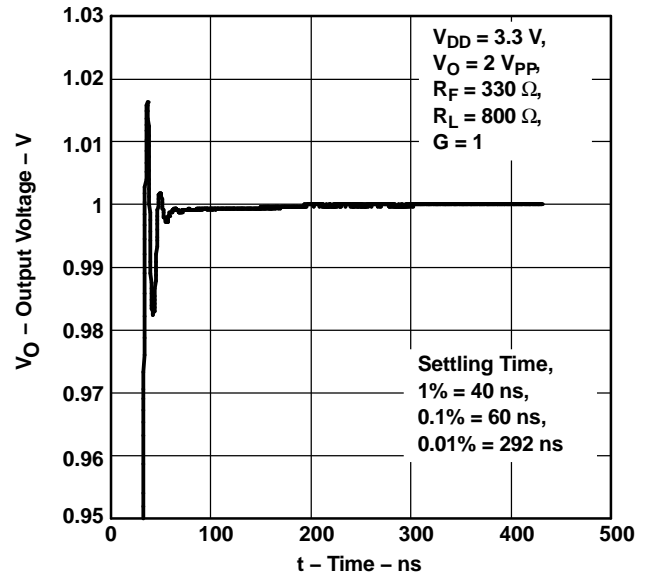


Figure 12.

VOLTAGE NOISE  
vs  
FREQUENCY

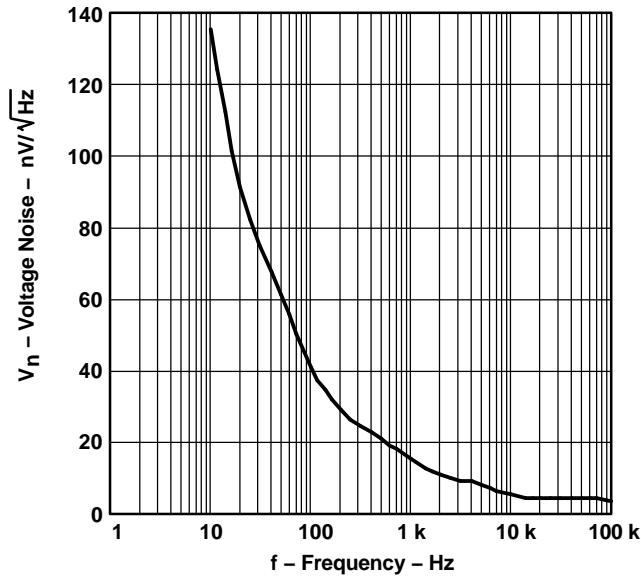


Figure 13.

OUTPUT OFFSET VOLTAGE  
vs  
COMMON-MODE INPUT VOLTAGE

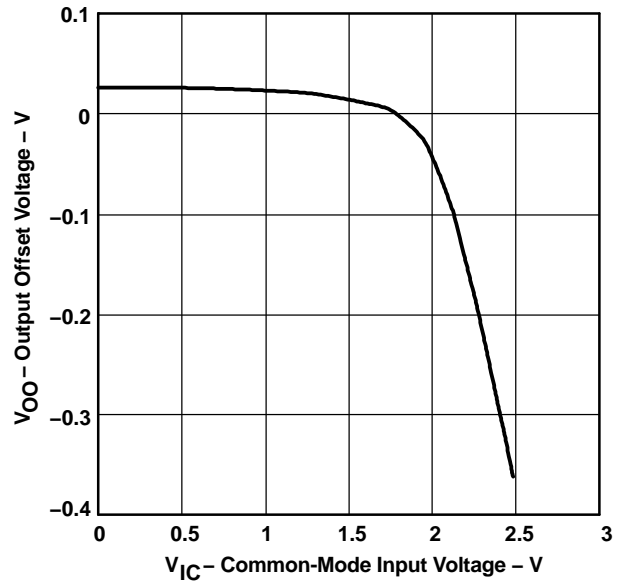


Figure 14.



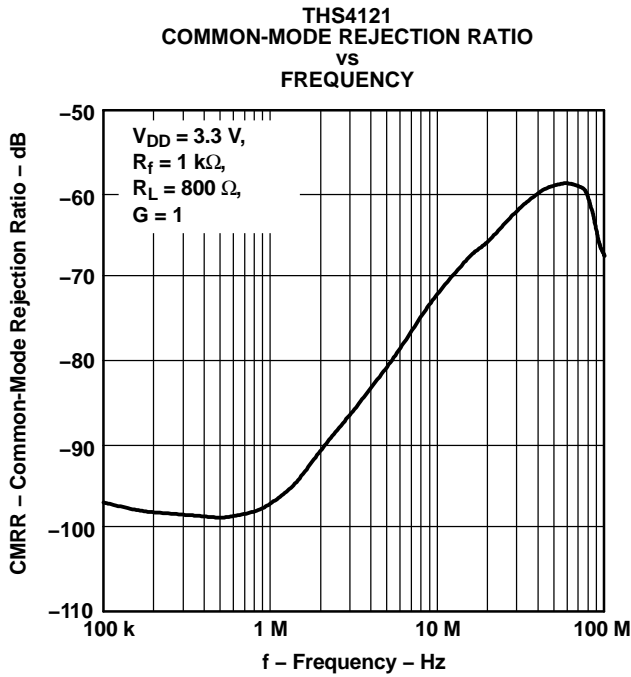


Figure 15.

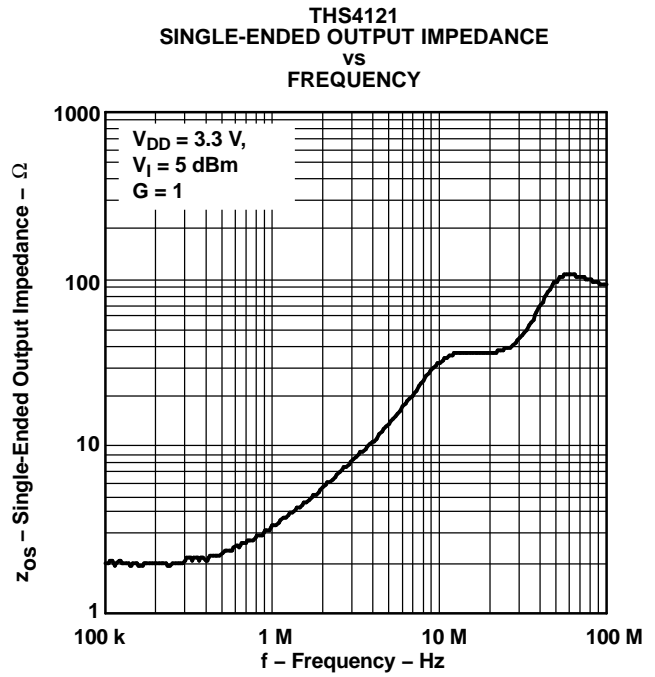


Figure 16.

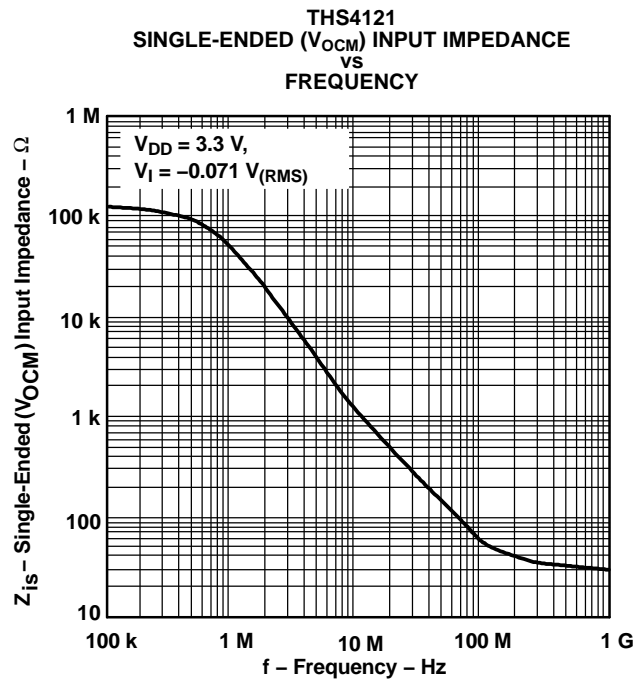


Figure 17.

## APPLICATION INFORMATION

### RESISTOR MATCHING

Resistor matching is important in fully differential amplifiers. The balance of the output on the reference voltage depends on matched ratios of the resistors. CMRR, PSRR, and cancellation of the second harmonic distortion diminish if resistor mismatch occurs. Therefore, it is recommended to use 1% tolerance resistors or better to keep the performance optimized.

$V_{OCM}$  sets the dc level of the output signals. If no voltage is applied to the  $V_{OCM}$  pin, it is set to the midrail voltage internally defined as:

$$\frac{(V_{DD}) + (V_{SS})}{2} \quad (1)$$

In the differential mode, the  $V_{OCM}$  on the two outputs cancel each other. Therefore, the output in the differential mode is the same as the input with the gain of 1.  $V_{OCM}$  has a high bandwidth capability up to the typical operation range of the amplifier. For the prevention of noise going through the device, use a 0.1- $\mu$ F capacitor on the  $V_{OCM}$  pin as a bypass capacitor. The following graph shows the simplified diagram of the THS412x.

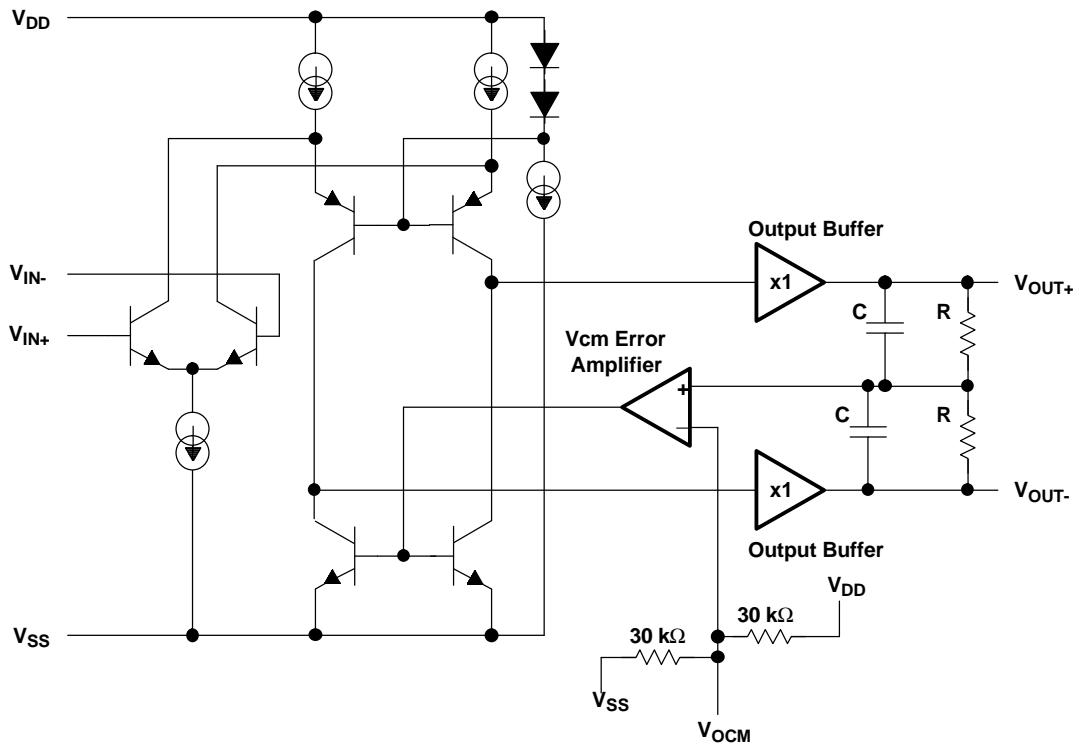
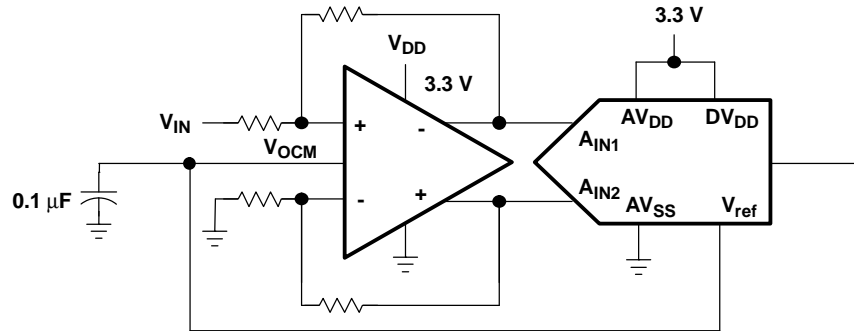


Figure 18. THS412x Simplified Diagram

## DATA CONVERTERS

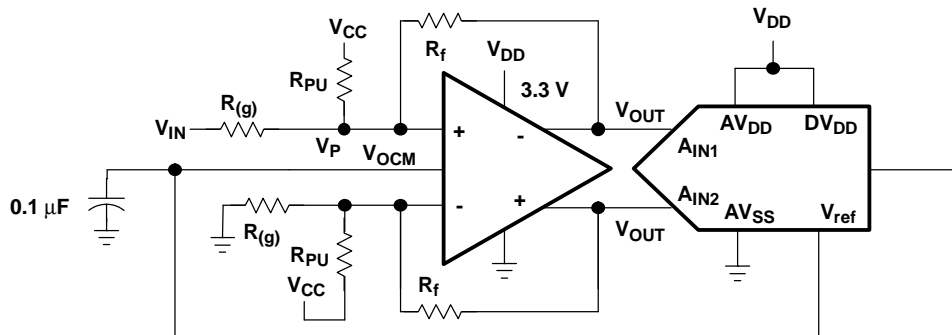
Data converters are one of the most popular applications for the fully differential amplifiers.

Fully differential amplifiers can operate with a single supply.  $V_{OCM}$  defaults to the midrail voltage,  $V_{DD}/2$ . The differential output may be fed into a data converter. This method eliminates the use of a transformer in the circuit. If the ADC has a reference voltage output ( $V_{ref}$ ), then it is recommended to connect it directly to the  $V_{OCM}$  of the amplifier using a bypass capacitor for stability. For proper operation, the input common-mode voltage to the input terminal of the amplifier should not exceed the common-mode input voltage range.



**Figure 19. Differential Amplifier Using a Single Supply**

Some single-supply applications may require the input voltage to exceed the common-mode input voltage range. In such cases, the following circuit configuration is suggested to bring the common-mode input voltage within the specifications of the amplifier.



**Figure 20. Circuit With Improved Common-Mode Input Voltage**

The following equation is used to calculate  $R_{PU}$ :

$$R_{PU} = \frac{V_P - V_{DD}}{(V_{IN} - V_P) \frac{1}{R_{(g)}} + (V_{OUT} - V_P) \frac{1}{R_f}}$$

(2)

## DRIVING A CAPACITIVE LOAD

Driving capacitive loads with high-performance amplifiers is not a problem as long as certain precautions are taken. The first is to realize that the THS412x has been internally compensated to maximize its bandwidth and slew rate performance. When the amplifier is compensated in this manner, capacitive loading directly on the output decreases the device's phase margin leading to high-frequency ringing or oscillations. Therefore, for capacitive loads of greater than 10 pF, it is recommended that a resistor be placed in series with the output of the amplifier, as shown in Figure 21. A minimum value of 20  $\Omega$  should work well for most applications. For example, in 50- $\Omega$  transmission systems, setting the series resistor value to 50  $\Omega$  both isolates any capacitance loading and provides the proper line impedance matching at the source end.

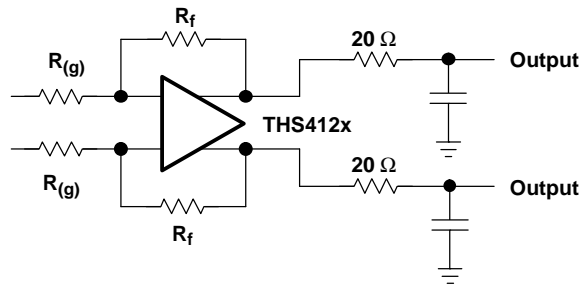


Figure 21. Driving a Capacitive Load

## ACTIVE ANTIALIAS FILTERING

For signal conditioning in ADC applications, it is important to limit the input frequency to the ADC. Low-pass filters can prevent the aliasing of the high-frequency noise with the frequency of operation. Figure 22 presents a method by which the noise may be filtered in the THS412x. Proper ground referencing should be considered.

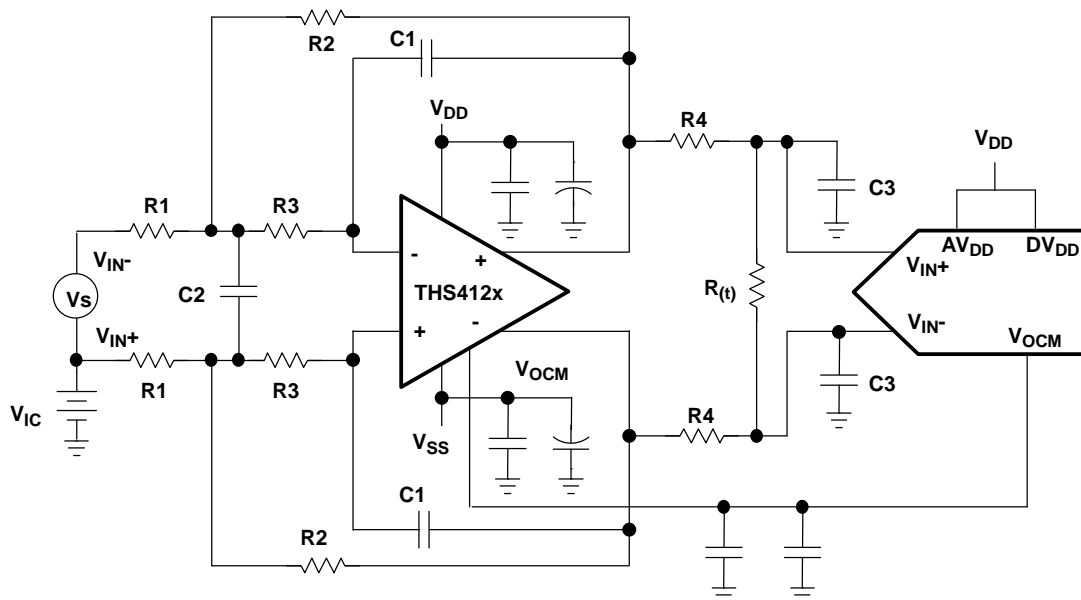


Figure 22. Antialias Filtering

The transfer function for this filter circuit is:

$$H_d(f) = \left[ \frac{K}{-\left(\frac{f}{\text{FSF} \times f_c}\right)^2 + \frac{1}{Q} \frac{jf}{\text{FSF} \times f_c} + 1} \right] \times \left[ \frac{\frac{R_t}{2R_4 + R_t}}{1 + \frac{j2\pi f R_4 R_t C_3}{2R_4 + R_t}} \right] \quad \text{Where } K = \frac{R_2}{R_1} \quad (3)$$

$$\text{FSF} \times f_c = \frac{1}{2\pi \sqrt{2 \times R_2 R_3 C_1 C_2}} \quad \text{and} \quad Q = \frac{\sqrt{2 \times R_2 R_3 C_1 C_2}}{R_3 C_1 + R_2 C_1 + K R_3 C_1} \quad (4)$$

K sets the pass-band gain,  $f_c$  is the cutoff frequency for the filter, FSF is a frequency scaling factor, and Q is the quality factor.

$$\text{FSF} = \sqrt{\text{Re}^2 + |\text{Im}|^2} \quad \text{and} \quad Q = \frac{\sqrt{\text{Re}^2 + |\text{Im}|^2}}{2\text{Re}} \quad (5)$$

Where Re is the real part, and Im is the imaginary part of the complex pole pair. Setting  $R_2 = R$ ,  $R_3 = mR$ ,  $C_1 = C$ , and  $C_2 = nC$  results in:

$$\text{FSF} \times f_c = \frac{1}{2\pi RC \sqrt{2 \times mn}} \quad \text{and} \quad Q = \frac{\sqrt{2 \times mn}}{1 + m(1 + K)} \quad (6)$$

Start by determining the ratios, m and n, required for the gain and Q of the filter type being designed, then select C and calculate R for the desired  $f_c$ .

## PRINCIPLES OF OPERATION

### THEORY OF OPERATION

The THS412x is a fully differential amplifier. Differential amplifiers are typically *differential in/single out*, whereas fully differential amplifiers are *differential in/differential out*.

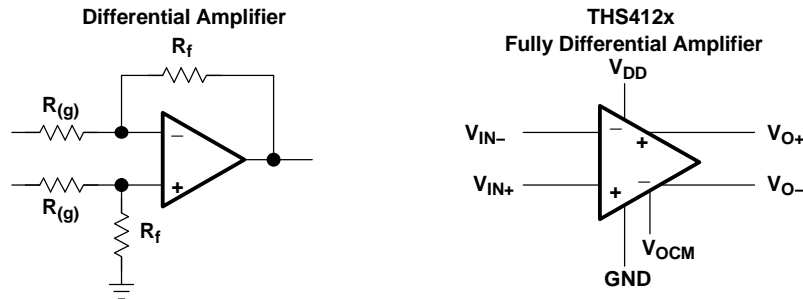


Figure 23. Differential Amplifier Versus a Fully Differential Amplifier

To understand the THS412x fully differential amplifiers, the definition for the pinouts of the amplifier are provided.

$$\text{Input voltage definition} \quad V_{ID} = (V_{I+}) - (V_{I-}) \quad V_{IC} = \frac{(V_{I+}) + (V_{I-})}{2} \quad (7)$$

$$\text{Output voltage definition} \quad V_{OD} = (V_{O+}) - (V_{O-}) \quad V_{OC} = \frac{(V_{O+}) + (V_{O-})}{2} \quad (8)$$

$$\text{Transfer function} \quad V_{OD} = V_{ID} \times A_{(f)} \quad (9)$$

$$\text{Output common-mode voltage } V_{OC} \quad (10)$$

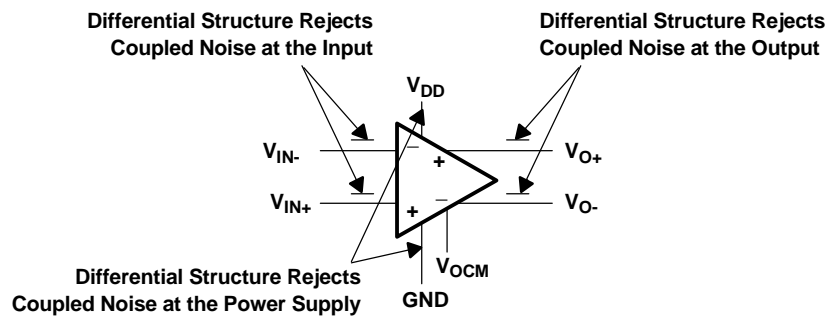


Figure 24. Definition of the Fully Differential Amplifier

The following schematics depict the differences between the operation of the THS412x, fully differential amplifier, in two different modes. Fully differential amplifiers can work with differential input or can be implemented as single in/differential out.

PRINCIPLES OF OPERATION (continued)

Note: For proper operation, maintain symmetry by setting  $R_{f1} = R_{f2} = R_f$  and  $R_{(g)1} = R_{(g)2} = R_{(g)}$   
 $\Rightarrow A = R_f/R_{(g)}$

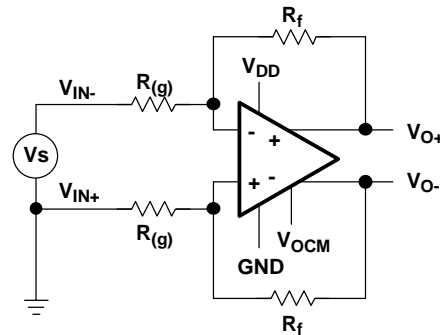
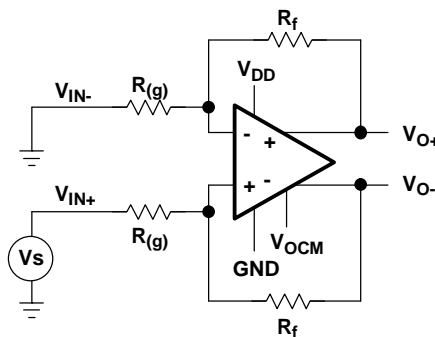


Figure 25. Amplifying Differential Signals



RECOMMENDED RESISTOR VALUES

GAIN	$R_{(g)}$ $\Omega$	$R_f$ $\Omega$
1	150	150

Figure 26. Single In With Differential Out

If each output is measured independently, each output is one-half of the input signal when gain is 1. The following equations express the transfer function for each output:

$$V_O = \frac{1}{2} V_I \tag{11}$$

The second output is equal and opposite in sign:

$$V_O = -\frac{1}{2} V_I \tag{12}$$

Fully differential amplifiers may be viewed as two inverting amplifiers. In this case, the equation of an inverting amplifier holds true for gain calculations. One advantage of fully differential amplifiers is that they offer twice as much dynamic range compared to single-ended amplifiers. For example, a 1- $V_{PP}$  ADC can only support an input signal of 1  $V_{PP}$ . If the output of the amplifier is 2  $V_{PP}$ , then it is not practical to feed a 2- $V_{PP}$  signal into the targeted ADC. Using a fully differential amplifier enables the user to break down the output into two 1- $V_{PP}$  signals with opposite signs and feed them into the differential input nodes of the ADC. In practice, the designer has been able to feed a 2-V peak-to-peak signal into a 1-V differential ADC with the help of a fully differential amplifier. The final result indicates twice as much dynamic range. Figure 27 illustrates the increase in dynamic range. The gain factor should be considered in this scenario. The THS412x fully differential amplifier offers an improved CMRR and PSRR due to its symmetrical input and output. Furthermore, second harmonic distortion is improved. Second harmonics tend to cancel because of the symmetrical output.

## PRINCIPLES OF OPERATION (continued)

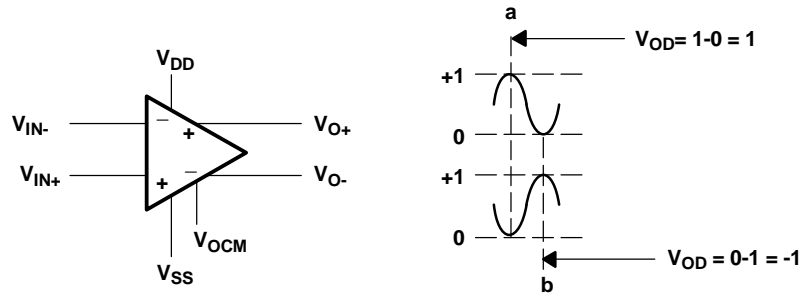


Figure 27. Fully Differential Amplifier With Two 1-V<sub>PP</sub> Signals

## CIRCUIT LAYOUT CONSIDERATIONS

To achieve the levels of high-frequency performance of the THS412x, follow proper printed-circuit board high frequency design techniques. A general set of guidelines is given below. In addition, a THS412x evaluation board is available to use as a guide for layout or for evaluating the device performance.

- Ground planes - It is highly recommended that a ground plane be used on the board to provide all components with a low inductive ground connection. However, in the areas of the amplifier inputs and output, the ground plane can be removed to minimize the stray capacitance.
- Proper power supply decoupling - Use a 6.8- $\mu$ F tantalum capacitor in parallel with a 0.1- $\mu$ F ceramic capacitor on each supply terminal. It may be possible to share the tantalum among several amplifiers depending on the application, but a 0.1- $\mu$ F ceramic capacitor should always be used on the supply terminal of every amplifier. In addition, the 0.1- $\mu$ F capacitor should be placed as close as possible to the supply terminal. As this distance increases, the inductance in the connecting trace makes the capacitor less effective. The designer should strive for distances of less than 0.1 inch between the device power terminals and the ceramic capacitors.
- Sockets - Sockets are not recommended for high-speed operational amplifiers. The additional lead inductance in the socket pins often lead to stability problems. Surface-mount packages soldered directly to the printed-circuit board is the best implementation.
- Short trace runs/compact part placements - Optimum high-frequency performance is achieved when stray series inductance has been minimized. To realize this, the circuit layout should be made as compact as possible, thereby minimizing the length of all trace runs. Particular attention should be paid to the inverting input of the amplifier. Its length should be kept as short as possible. This helps to minimize stray capacitance at the input of the amplifier.
- Surface-mount passive components - Using surface-mount passive components is recommended for high-frequency amplifier circuits for several reasons. First, because of the extremely low lead inductance of surface-mount components, the problem with stray series inductance is greatly reduced. Second, the small size of surface-mount components naturally leads to a more compact layout thereby minimizing both stray inductance and capacitance. If leaded components are used, it is recommended that the lead lengths be kept as short as possible.

## POWER-DOWN MODE

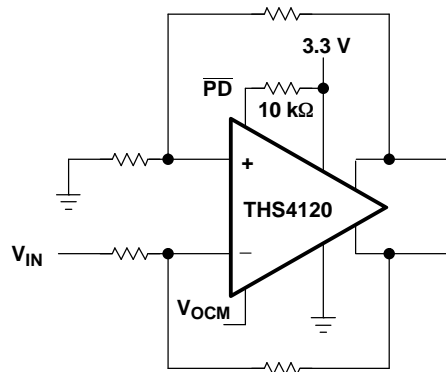
The THS4120 features a power-down pin ( $\overline{PD}$ ) which lowers the quiescent current from 11 mA down to 120  $\mu$ A, ideal for reducing system power. The power-down pin of the amplifier must be pulled high via a 10-k $\Omega$  pullup resistor between the  $\overline{PD}$  pin and the positive supply (see Figure 28) in the absence of an applied voltage, putting the amplifier in the power-on mode of operation. To turn off (disable) the amplifier in an effort to conserve power, the power-down pin can be driven towards the negative rail or ground. The threshold voltages for power-on and power-down are relative to the supply rails and given in the specification tables. Above the *Enable Threshold Voltage*, the device is on. Below the *Disable Threshold Voltage*, the device is off. Behavior in between these threshold voltages is not specified.

Note that this power-down functionality is just that; the amplifier consumes less power in power-down mode. The power-down mode is not intended to provide a high-impedance output. The power-down functionality is not intended to allow use as a 3-state bus driver. When in power-down mode, the impedance looking back into the output of the amplifier is dominated by the feedback and gain-setting resistors, but the output impedance of the device itself varies depending on the voltage applied to the outputs.

The time delays associated with turning the device on and off are specified as the time it takes for the amplifier to reach 50% of the nominal quiescent current. The enable time delay is in the order of microseconds due to the amplifier moving in and out of the linear mode of operation.

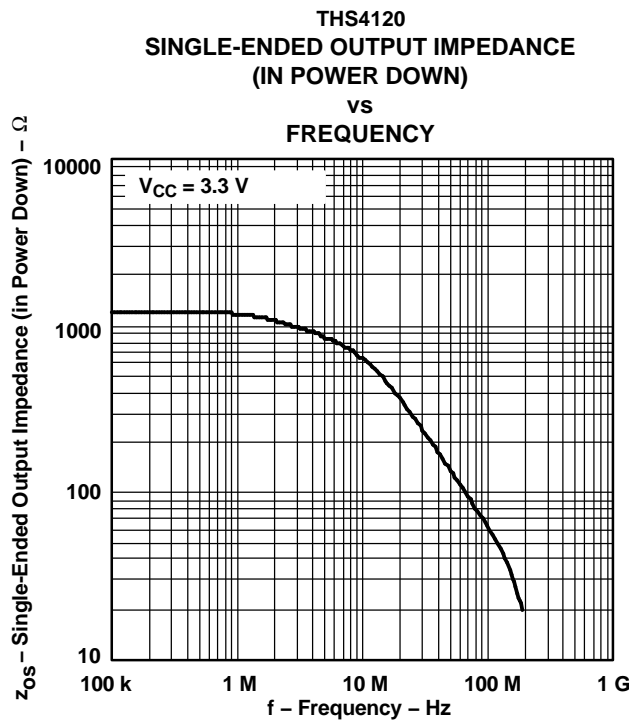


**PRINCIPLES OF OPERATION (continued)**



**Figure 28.**

Due to the similarity of the standard inverting amplifier configuration, the output impedance appears to be low while in the power-down state. This is because the feedback resistor ( $R_f$ ) and the gain resistor ( $R_{(g)}$ ) are still connected to the circuit. Therefore, a current path is allowed between the input of the amplifier and the output of the amplifier. An example of the closed-loop output impedance is shown in Figure 29.



**Figure 29.**

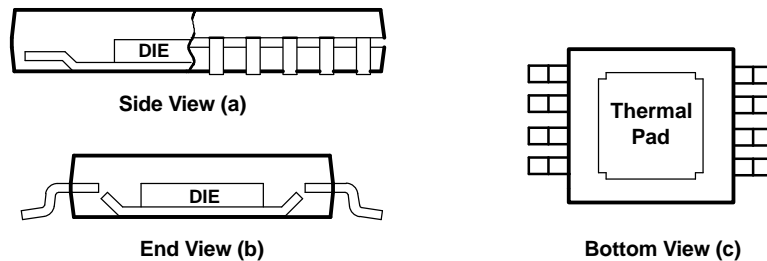
## GENERAL PowerPAD DESIGN CONSIDERATIONS (APPLICABLE TO DIFFERENTIAL AMPLIFIER FAMILY)

The THS412x is available packaged in a thermally enhanced DGN package, which is a member of the PowerPAD family of packages. This package is constructed using a downset leadframe on which the die is mounted [see Figure 30(a) and Figure 30(b)]. This arrangement results in the leadframe being exposed as a thermal pad on the underside of the package [see Figure 30(c)]. Because this thermal pad has direct thermal contact with the die, excellent thermal performance can be achieved by providing a good thermal path away from the thermal pad.

The PowerPAD package allows for both assembly and thermal management in one manufacturing operation. During the surface-mount solder operation (when the leads are being soldered), the thermal pad can also be soldered to a copper area underneath the package. Through the use of thermal paths within this copper area, heat can be conducted away from the package into either a ground plane or other heat-dissipating device.

The PowerPAD package represents a breakthrough in combining the small area and ease of assembly of the surface mount with the, heretofore, awkward mechanical methods of heatsinking.

More complete details of the PowerPAD installation process and thermal management techniques can be found in the Texas Instruments Technical Brief, *PowerPAD Thermally Enhanced Package* (SLMA002). This document can be found at the TI Web site (www.ti.com) by searching on the key word PowerPAD. The document can also be ordered through your local TI sales office. Refer to literature number [SLMA002](#) when ordering.



- A. The thermal pad is electrically isolated from all terminals in the package.

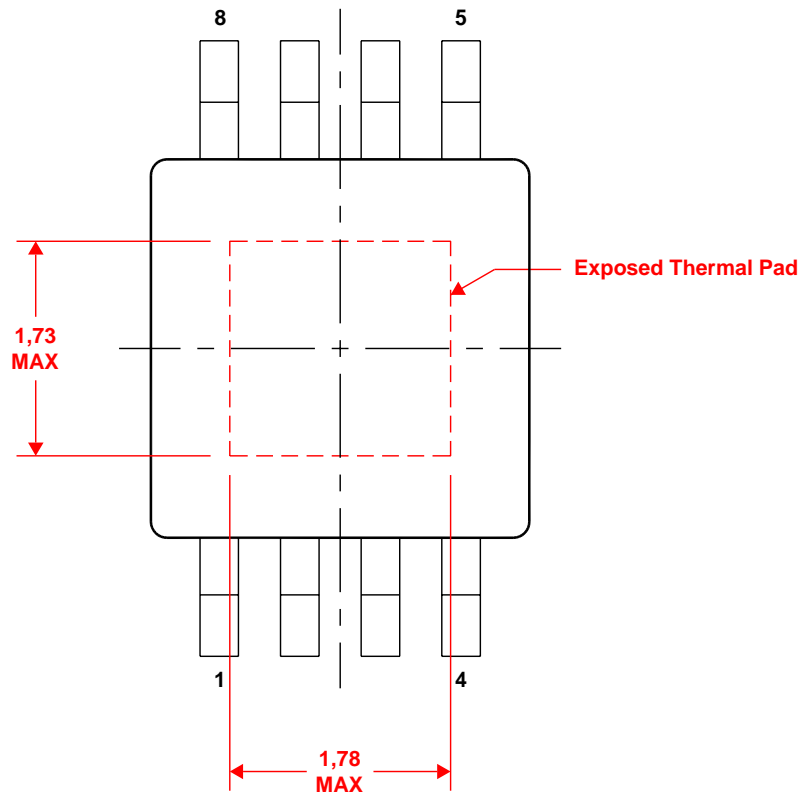
**Figure 30. Views of Thermally Enhanced DGN Package**

## THERMAL INFORMATION

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. When the thermal pad is soldered directly to the printed circuit board (PCB), the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to a ground plane or special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, *PowerPAD Thermally Enhanced Package*, Texas Instruments Literature No. SLMA002 and Application Brief, *PowerPAD Made Easy*, Texas Instruments Literature No. SLMA004. Both documents are available at [www.ti.com](http://www.ti.com).

The exposed thermal pad dimensions for this package are shown in the following illustration.



Top View

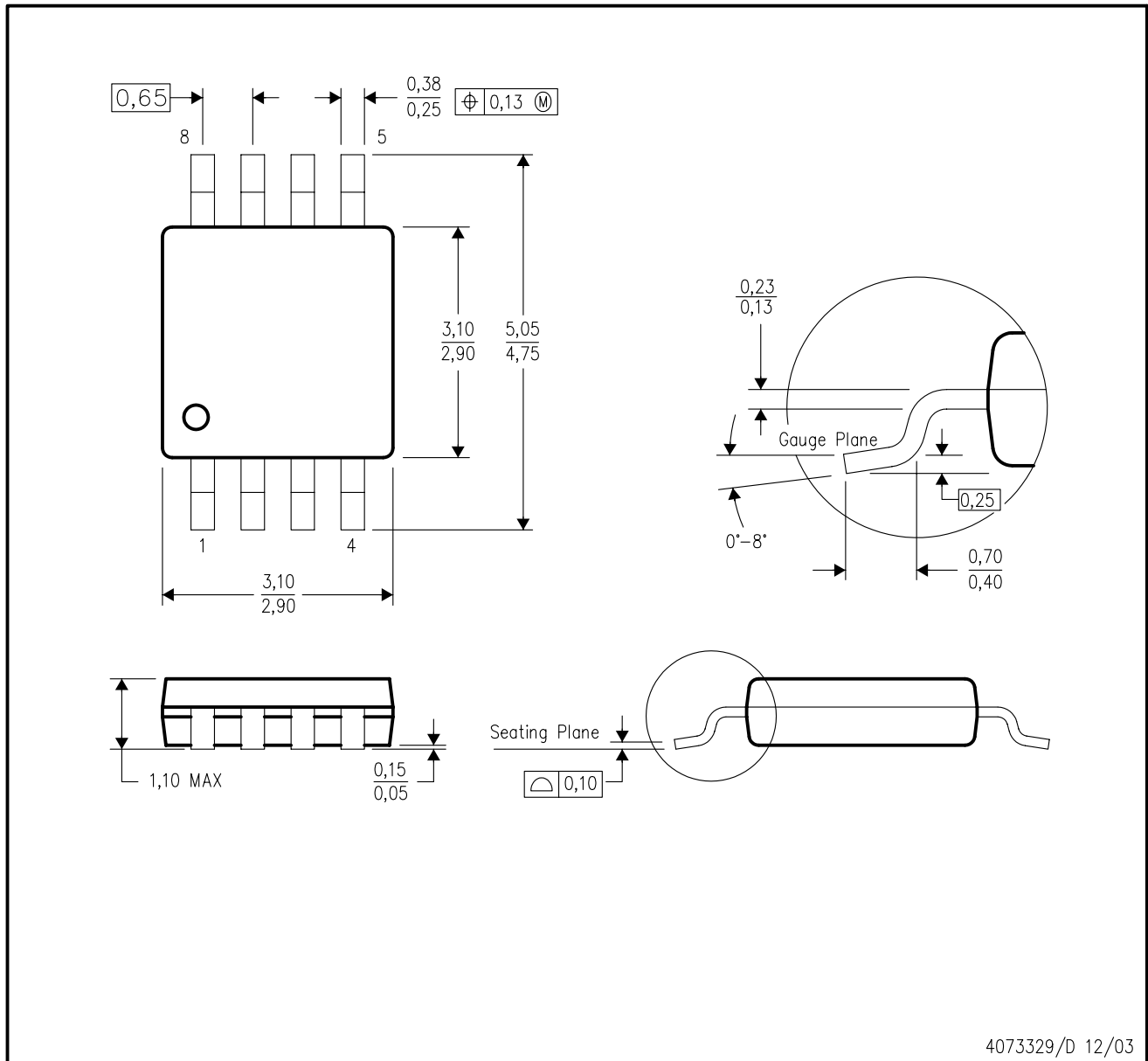
NOTE: All linear dimensions are in millimeters

PPTD041

### Exposed Thermal Pad Dimensions

DGK (S-PDSO-G8)

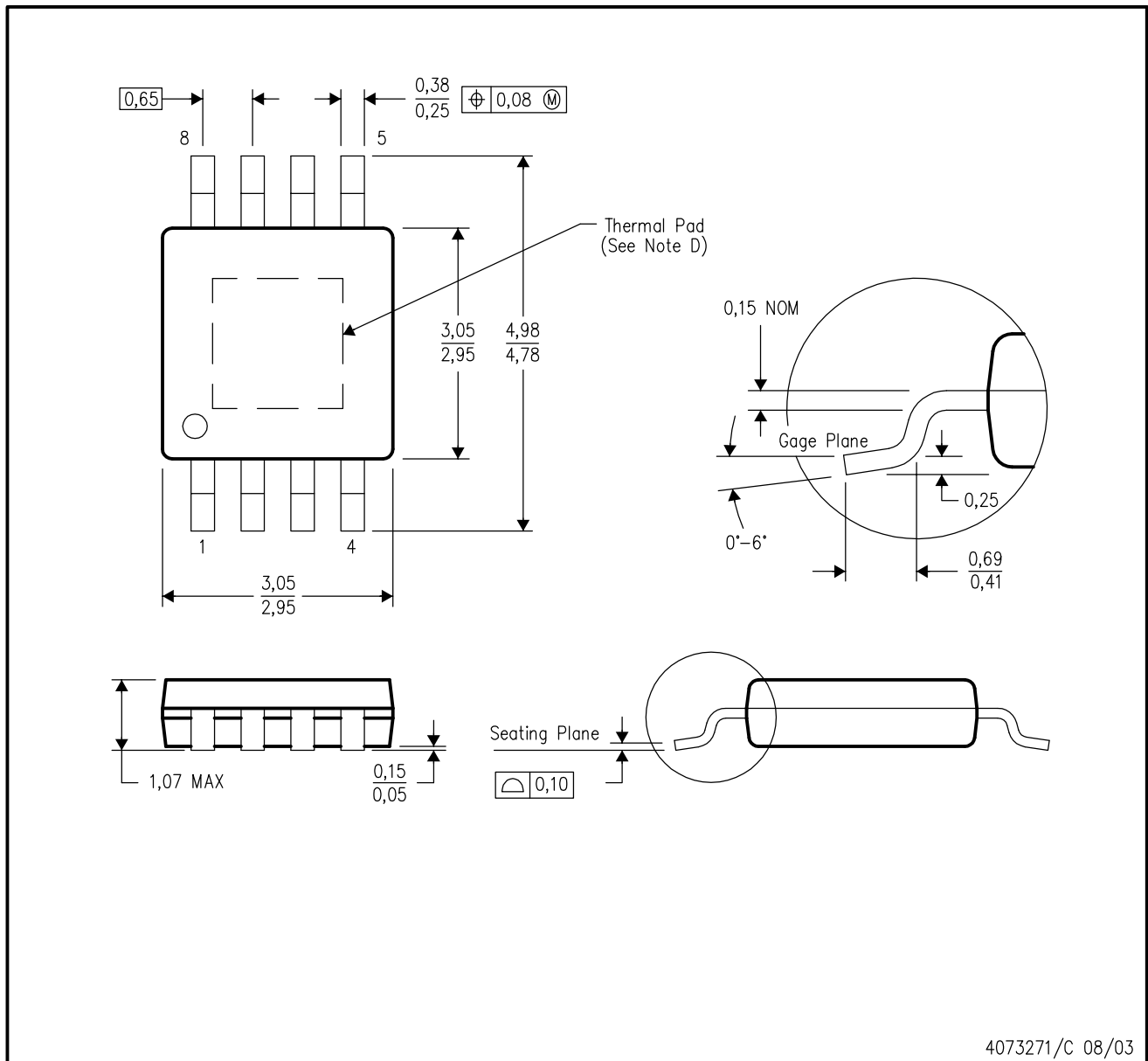
PLASTIC SMALL-OUTLINE PACKAGE



- NOTES:
- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Body dimensions do not include mold flash or protrusion.
  - D. Falls within JEDEC MO-187 variation AA.

DGN (S-PDSO-G8)

PowerPAD™ PLASTIC SMALL-OUTLINE PACKAGE



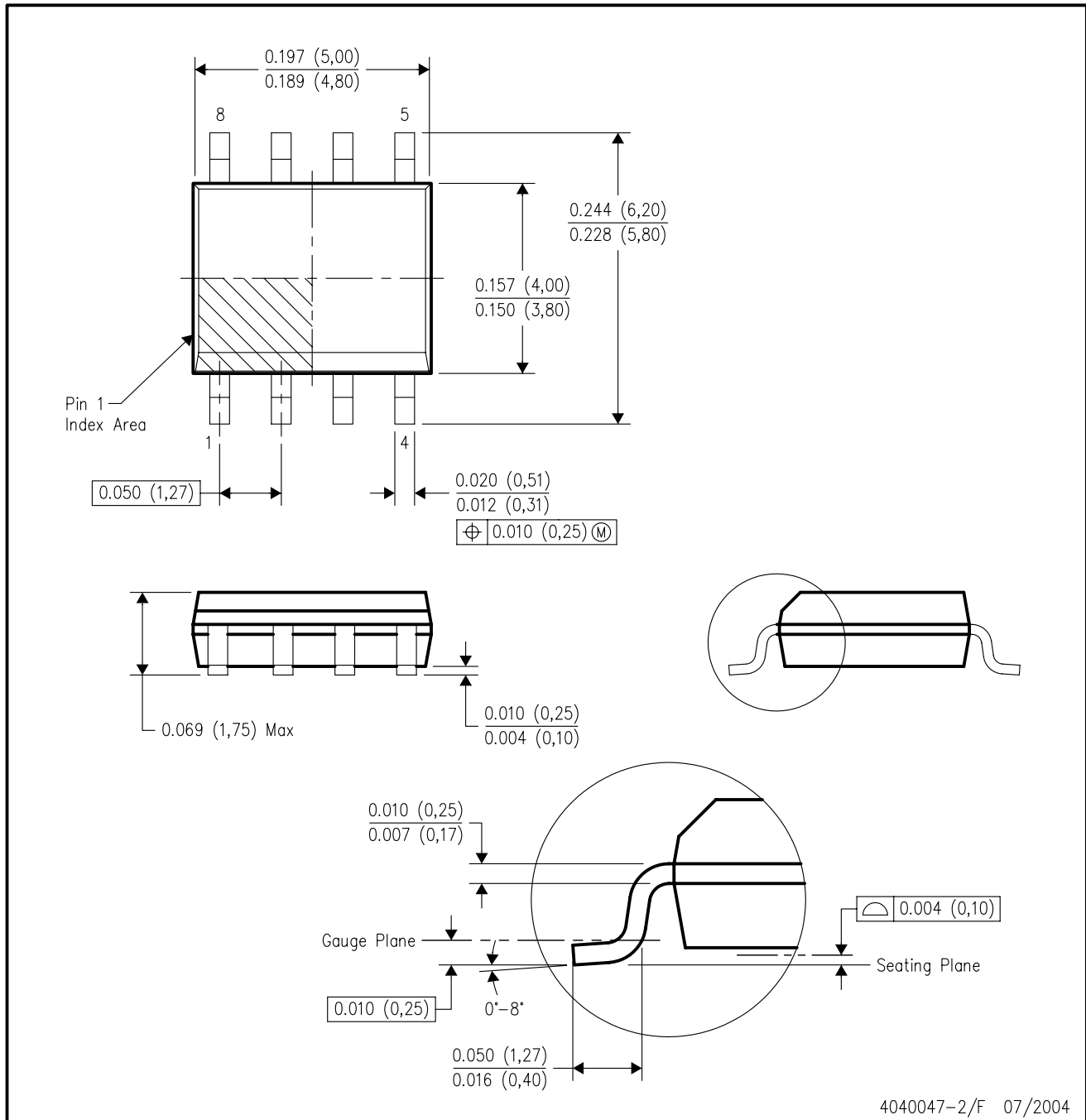
4073271/C 08/03

- NOTES:
- All linear dimensions are in millimeters.
  - This drawing is subject to change without notice.
  - Body dimensions do not include mold flash or protrusion.
  - This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>.
  - Falls within JEDEC MO-187

PowerPAD is a trademark of Texas Instruments.

D (R-PDSO-G8)

PLASTIC SMALL-OUTLINE PACKAGE



- NOTES:
- A. All linear dimensions are in inches (millimeters).
  - B. This drawing is subject to change without notice.
  - C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
  - D. Falls within JEDEC MS-012 variation AA.

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DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>	Broadband	<a href="http://www.ti.com/broadband">www.ti.com/broadband</a>
Interface	<a href="http://interface.ti.com">interface.ti.com</a>	Digital Control	<a href="http://www.ti.com/digitalcontrol">www.ti.com/digitalcontrol</a>
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